On selecting leaves with disjoint neighborhoods in embedded trees

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Introduction

This work focuses on a **generalization** of a **combinatorial result** by A. Aggarwal, L. Giubas, J. Saxe and P. Shor [DCG 1987].

Given an embedded tree, the goal is to select in **linear time** a **constant fraction** of the leaves.

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Part of an algorithm to construct in deterministic **linear time** the: **Voronoi Diagram of points in convex position**, given the convex hull.

Can also be extended to other Voronoi diagrams with **tree structure**:

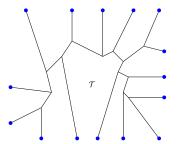
- → Farthest point VD, given the convex hull.
- → Update of a VD, after deleting a point.
- \rightarrow Order-k VD, given the order-(k-1) VD.

Applications

- The algorithmic scheme has been used to derive linear time algorithms for many problems, e.g.:
 - → **Medial axis** of a simple polygon in O(n). [Chin et al. DCG 1999]
 - → Order-k VD in $O(nk^2 + n \log n)$. [D.T. Lee - IEEE Trans. Comput. 1982]
 - \rightarrow Hamiltonian Abstract VD in O(n). [Klein and Lingas ISAAC 1994]
 - \rightarrow Forest-like Abstract VD in O(n). [Bohler et al. Comp. Geom. 2014]

Theorem [Aggarwal et al. 1987]

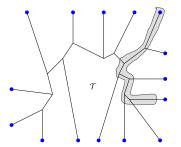
Let T be an embedded binary tree with n leaves



Theorem [Aggarwal et al. 1987]

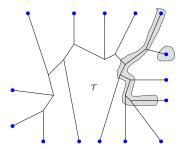
Let \mathcal{T} be an embedded binary tree with n leaves where:

i) Each leaf of ${\mathcal T}$ has a neighborhood - (a subtree of ${\mathcal T}$).



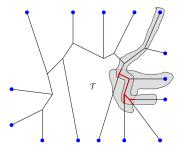
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- i) Each leaf of \mathcal{T} has a neighborhood (a subtree of \mathcal{T}).
- ii) Topologically consecutive leaves have disjoint neighborhoods.



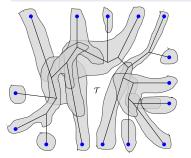
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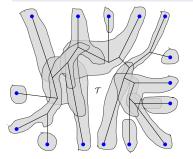
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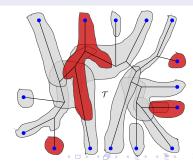
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i) $\exists \geq \frac{1}{10}n$ leaves with pairwise disjoint neighborhoods.





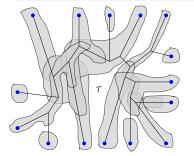
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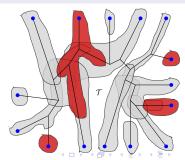
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- i) $\exists \geq \frac{1}{10}n$ leaves with pairwise disjoint neighborhoods.
- ii) These leaves can be found in O(n) time.





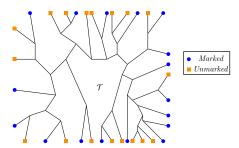
└─ Original algorithm

Our result

Theorem - Generalized

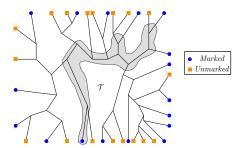
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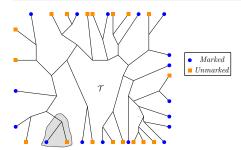
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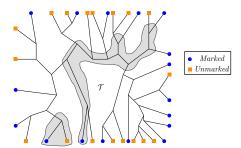
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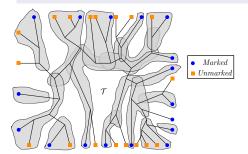
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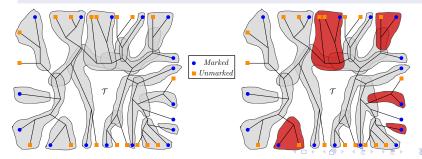
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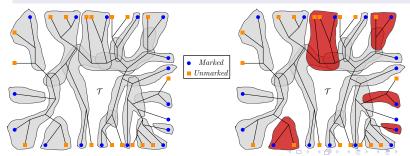
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Remarks:

■ If the solution is required to be a constant fraction of m, then it suffices to choose any constant for $p \in (0,1)$.

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Remarks:

- If the solution is required to be a constant fraction of m, then it suffices to choose any constant for $p \in (0,1)$.
- If p is a constant, then the algorithm has O(n) time complexity.

Motivation

Linear-time algorithms for problems mentioned (e.g. deletion of a site, construction of order-k, etc.) remain open for:

- Voronoi diagram of non-point sites ...even for simple sites as circles, line segments, etc.
- Abstract Voronoi diagrams

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Suggests that, to potentially apply the linear-time framework... ... We first need this **generalized combinatorial result.**

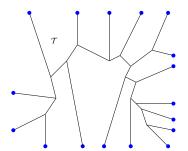
Outline of results

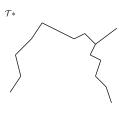
1. Present some necessary **preliminaries**.

2. Show the first part of the theorem, the **existence**.

3. Show the second part of the theorem, the **algorithm**.

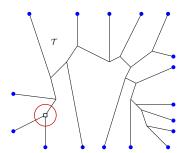
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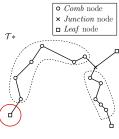




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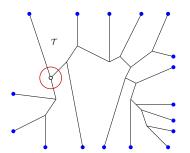
Leaf node if deg(u) = 1 in \mathcal{T}^* .

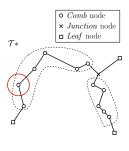




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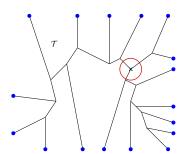


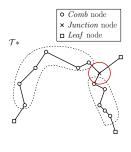


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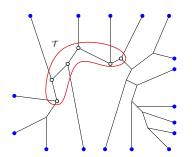


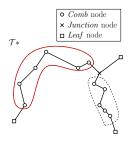
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A **spine** is a maximal sequence of consecutive *Comb* nodes.



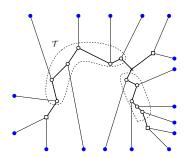


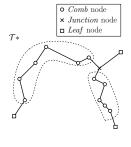
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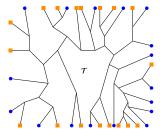
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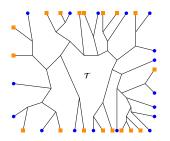




Labeling the tree ${\mathcal T}$

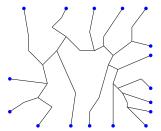


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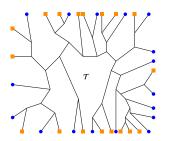


Transformation:

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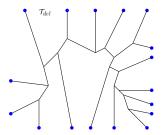


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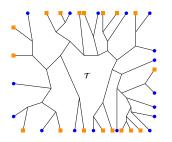


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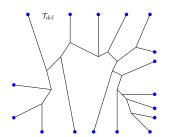


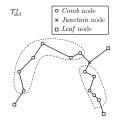
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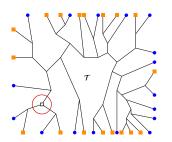
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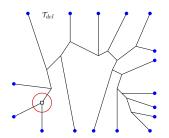


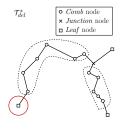
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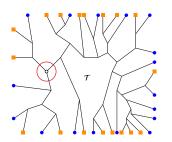
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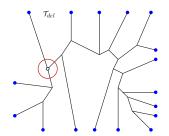


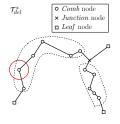
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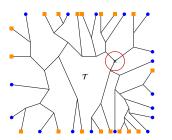
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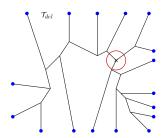


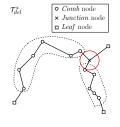
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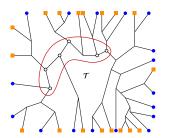
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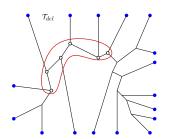
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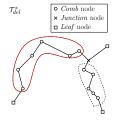
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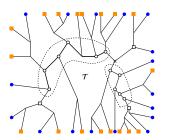
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Spine: A sequence of consecutive Comb nodes.

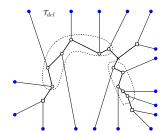


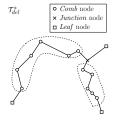


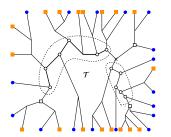


Remark:

Original: All internal nodes get labeled. Generalized: Only a subset of the internal nodes get labeled.





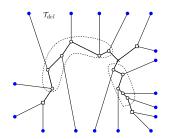


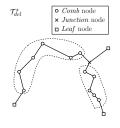
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Idea:

Pass the information of the marked leaves to a subset of \mathcal{T} to resemble [Aggarwal et al. 1987].





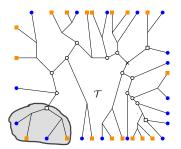
Preliminaries

Components

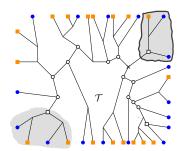
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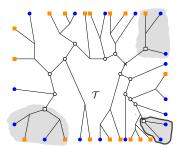
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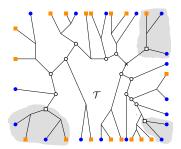
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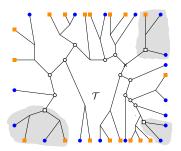


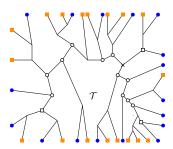
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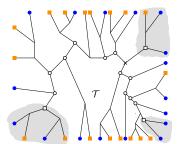
L-component: The Leaf node and the 2 subtrees hanging off that node. Subdivide each spine into groups of 5 Comb nodes.





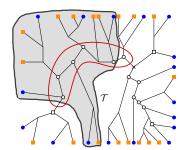
Define two types of components, which are subtrees of \mathcal{T} .

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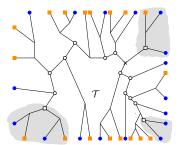
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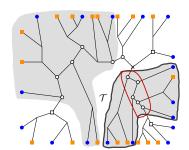
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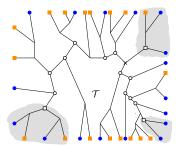
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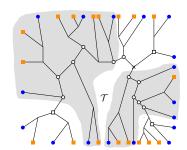
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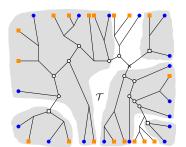
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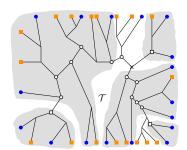
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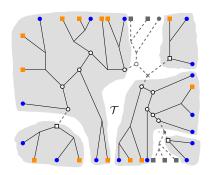


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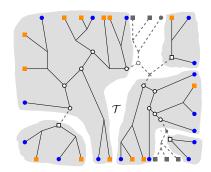
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- 5-component



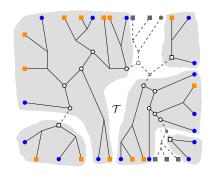
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Observations:

lacksquare Components are disjoint subtrees of \mathcal{T} .

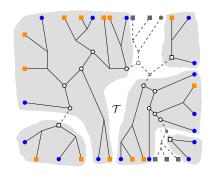
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Observations:

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- Each *L*-component has 2 marked leaves.
- Each 5-component has 5 marked leaves.

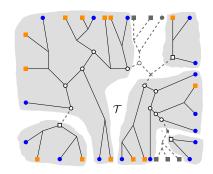
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- Not every node belongs to a component.
- A component can have $\Theta(n)$ nodes.



☐ Existence

Existence

We want to prove:

Lemma - Existence

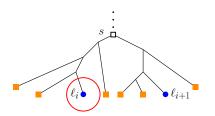
At least $\frac{1}{10}m$ marked leaves of $\mathcal T$ have pairwise disjoint neighborhoods.

Lemma 1

In every component, there a exists at least one marked leaf ℓ with neighborhood $nh(\ell)$ confined to that component.

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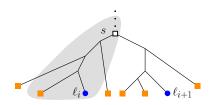
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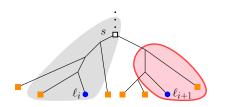


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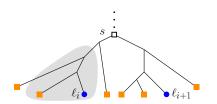


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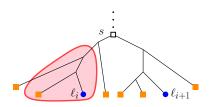


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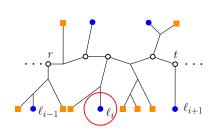
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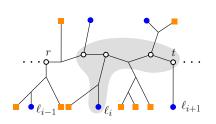
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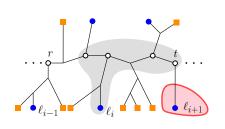


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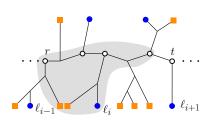


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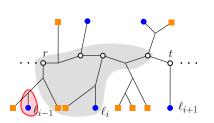


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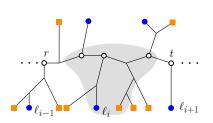


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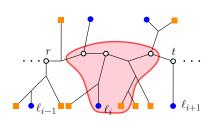


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Existence

Corrolary - Lemma 1

The number of marked leaves with a confined neighborhood is:

- \rightarrow At least 1 out of 5 in every 5-component.
- \rightarrow At least 1 out of 2 in every *L*-component.

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Observation

Each spine has at most 4 ungrouped Comb nodes.

Lemma 2

For every 8 ungrouped *Comb* nodes there exists at least 1 *L*-component.

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Combining the above, we conclude:

Lemma - Existence

At least $\frac{1}{10}m$ marked leaves have pairwise disjoint neighborhoods.

Goal: Design an algorithm to return a fraction of the marked leaves with pairwise disjoint neighborhoods.

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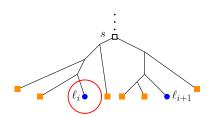
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Introduce a parameter $p \in (0,1)$ in the algorithm.

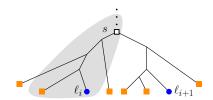
Trade-off between time complexity and number of selected leaves.

- 1. Label the tree ${\cal T}$ and obtain the components.
- 2. For each component K check up to a fixed number of steps O(z):

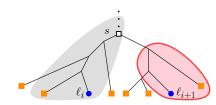
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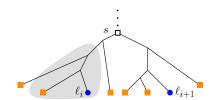
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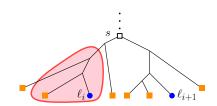
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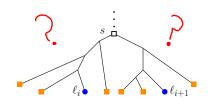
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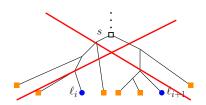
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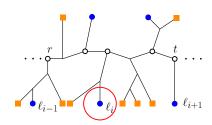
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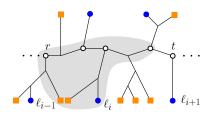
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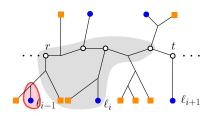
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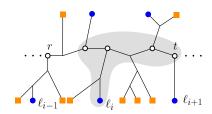
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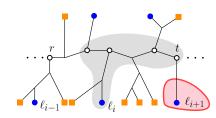
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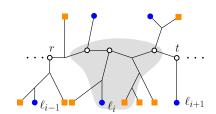
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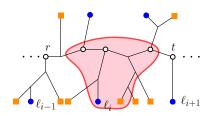
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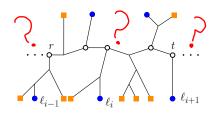
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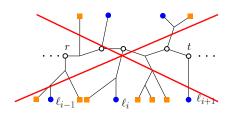
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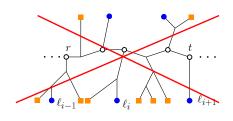
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5. Return selected leaves.

Algorithm proofs

Need to show:

Algorithm Correctness

Lemma - Correctness

The algorithm returns at least $\frac{p}{10}m$ leaves with pairwise disjoint neighborhoods.

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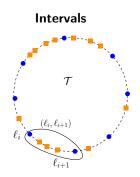
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Algorithm time complexity

Lemma -Time complexity

The algorithm has time complexity $O(\frac{1}{1-p}n)$.



Idea:

Lower bound the number of intervals that do not have *many* unmarked leaves.

Intervals \mathcal{T}

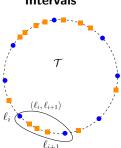
Idea:

Lower bound the number of intervals that do not have many unmarked leaves.

Lemma - Pigeonhole

Let M_{\times} be the number of marked leaves whose intervals have at most x unmarked leaves, $x \in \mathbb{N}$. Then $|M_x| \geq \frac{x-c+1}{x+1}m$ holds.

Intervals

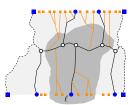


c is the ratio between unmarked and marked leaves, $c = \left\lceil \frac{n-m}{m} \right\rceil$.

Idea:

Upper bound the size of a confined neighborhood by the number of unmarked leaves in the intervals related to the component.

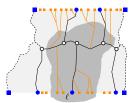




Idea:

Upper bound the size of a confined neighborhood by the number of unmarked leaves in the intervals related to the component.





Lemma - Size of confined neighborhoods

Let K be component and a marked leaf ℓ with neighborhood $nh(\ell)$ confined K. Then, $|nh(\ell)| < 10\delta_K$.

 δ_K is the maximum size of intervals related to the component K.

Time complexity proof

Lemma -Time complexity

The algorithm has time complexity $O(\frac{1}{1-n}n)$.

■ There are $\Theta(m)$ components.

Time complexity proof

Lemma -Time complexity

The algorithm has time complexity $O(\frac{1}{1-p}n)$.

- There are $\Theta(m)$ components.
- For each component, the algorithm does a fixed number of steps $(\leq 10z)$.

By using
$$z = \left\lceil \frac{10c}{1-p} \right\rceil = \Theta(\frac{c}{1-p})$$
, the claim follows.

Conclusion

Theorem - Generalized

Let \mathcal{T} be an embedded binary tree with n leaves where:

- i) m of the leaves have been marked.
- ii) Each marked leaf of \mathcal{T} has a neighborhood.
- iii) Topologically consecutive marked leaves have disjoint neighborhoods. Then:
- i) $\exists \geq \frac{1}{10}m$ marked leaves with pairwise disjoint neighborhoods.
- $(ii) \ge \frac{p}{10}m$ marked leaves can be found in $O(\frac{1}{1-p}n)$ time, $p \in (0,1)$.

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- i) m of the leaves have been marked.
- ii) Each marked leaf of \mathcal{T} has a neighborhood.
- iii) Topologically consecutive marked leaves have disjoint neighborhoods. Then:
- i) $\exists \geq \frac{1}{10}m$ marked leaves with pairwise disjoint neighborhoods.
- $(ii) \geq \frac{p}{10}m$ marked leaves can be found in $O(\frac{1}{1-p}n)$ time, $p \in (0,1)$.

Expect it to be helpful in designing deterministic linear time algorithms for problems related to abstract Voronoi diagrams and other generalized Voronoi diagrams.

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Thank you for your attention!

