

The Voronoi Diagram of Rotating Rays with applications to Floodlight Illumination

Ioannis Mantas²

Carlos Alegría¹ Evanthia Papadopoulou² Marko Savić³
Hendrik Schrezenmaier⁴ Carlos Seara⁵ Martin Suderland²

1. Università Roma Tre, Rome, Italy
2. **Università della Svizzera italiana, Lugano, Switzerland**
3. University of Novi Sad, Novi Sad, Serbia
4. Technische Universität Berlin, Berlin, Germany
5. Universitat Politècnica de Catalunya, Barcelona, Spain

EuroCG 2021
Saint Petersburg, Russia

Table of Contents

Introduction

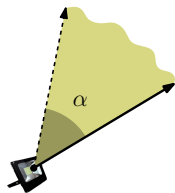
RVD Definitions & Properties

RVD in the Plane

RVD of a Convex Polygon

Brocard Illumination

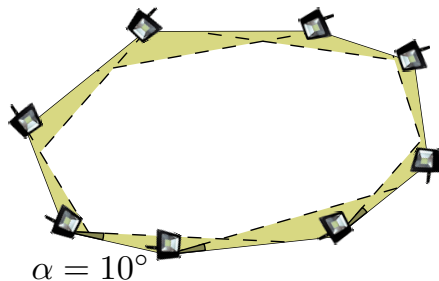
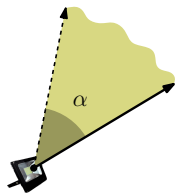
α -floodlight



Brocard Illumination

Input: Polygon P with edge-aligned α -floodlights

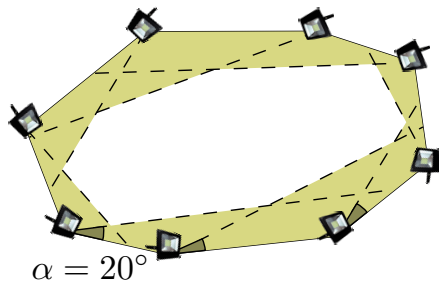
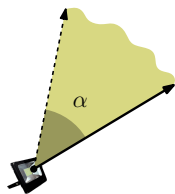
α -floodlight



Brocard Illumination

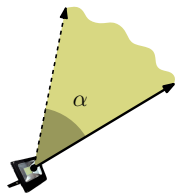
Input: Polygon P with edge-aligned α -floodlights

α -floodlight



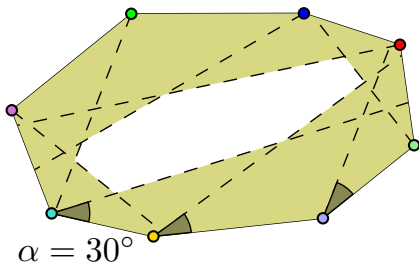
Brocard Illumination

α -floodlight



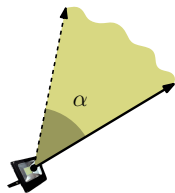
Input: Polygon P with edge-aligned α -floodlights

Goal: Minimum angle α^* to illuminate P



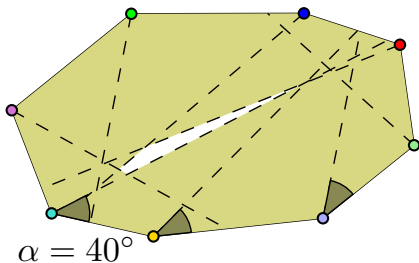
Brocard Illumination

α -floodlight



Input: Polygon P with edge-aligned α -floodlights

Goal: Minimum angle α^* to illuminate P



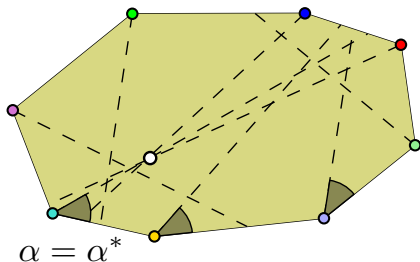
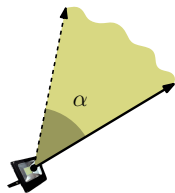
Brocard Illumination

Brocard illumination problem

Input: Polygon P with edge-aligned α -floodlights

Goal: Minimum angle α^* to illuminate P

α -floodlight



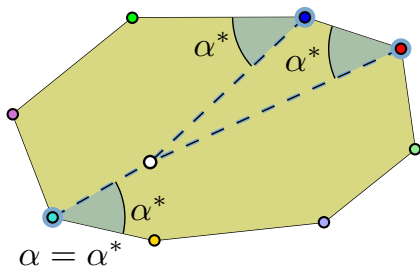
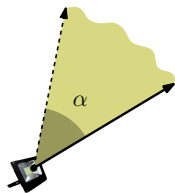
Brocard Illumination

Brocard illumination problem

Input: Polygon P with edge-aligned α -floodlights

Goal: Minimum angle α^* to illuminate P

α -floodlight

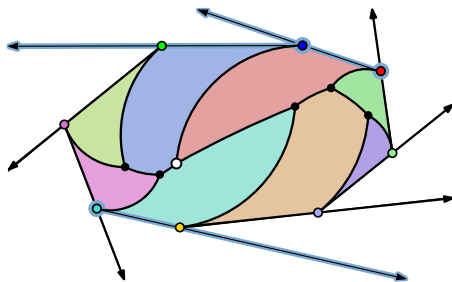
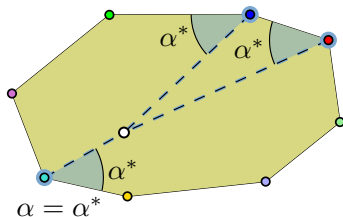


Brocard Illumination

Input: Polygon P with edge-aligned α -floodlights.

Goal: Minimum angle α^* to illuminate P .

Approach: Define the **Voronoi Diagram of Rotating Rays**.



Related Work

Brocard Polygons - Illumination

- ▶ Brocard Polygons (only harmonic polygons)
e.g. [Casey 1888, Dmitriev & Dynkin 1946, Bernhart 1959]

Related Work

Brocard Polygons - Illumination

- ▶ Brocard Polygons (only harmonic polygons)
e.g. [Casey 1888, Dmitriev & Dynkin 1946, Bernhart 1959]
- ▶ Brocard Illumination - Brocard angle [Alegría et al. 2017]
 $O(n^3 \log^2 n)$ time, $O(n \log n)$ time convex polygons

Related Work

Brocard Polygons - Illumination

- ▶ Brocard Polygons (only harmonic polygons)
e.g. [Casey 1888, Dmitriev & Dynkin 1946, Bernhart 1959]
- ▶ Brocard Illumination - Brocard angle [Alegría et al. 2017]
 $O(n^3 \log^2 n)$ time, $O(n \log n)$ time convex polygons

Floodlight Illumination

- ▶ Several variants/results, e.g. [Bose et al. 1993, Uruttia 2000]
- ▶ Uniform angle, e.g. [O'Rourke 1995, Toth 2002]

Related Work

Brocard Polygons - Illumination

- ▶ Brocard Polygons (only harmonic polygons)
e.g. [Casey 1888, Dmitriev & Dynkin 1946, Bernhart 1959]
- ▶ Brocard Illumination - Brocard angle [Alegría et al. 2017]
 $O(n^3 \log^2 n)$ time, $O(n \log n)$ time convex polygons

Floodlight Illumination

- ▶ Several variants/results, e.g. [Bose et al. 1993, Uruttia 2000]
- ▶ Uniform angle, e.g. [O'Rourke 1995, Toth 2002]

Application - Domain coverage

- ▶ Directional Antennas or Surveillance Cameras [Berman et al. 2007, Kranakis et al. 2011, Neishaboori et al. 2014, Czyzowicz et al. 2015]

Table of Contents

Introduction

RVD Definitions & Properties

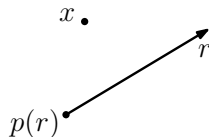
RVD in the Plane

RVD of a Convex Polygon

Angular distance - bisectors

Definition

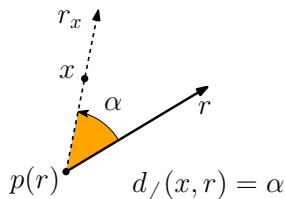
Given a ray r and a point $x \in \mathbb{R}^2$, the **angular distance** from x to r , $d_{\angle}(x, r)$,



Angular distance - bisectors

Definition

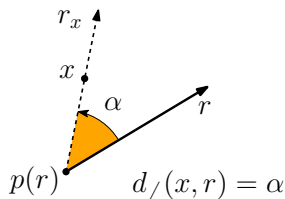
Given a ray r and a point $x \in \mathbb{R}^2$, the **angular distance** from x to r , $d_{\angle}(x, r)$, is the minimum counterclockwise angle α from r to a ray with apex $p(r)$ passing through x .



Angular distance - bisectors

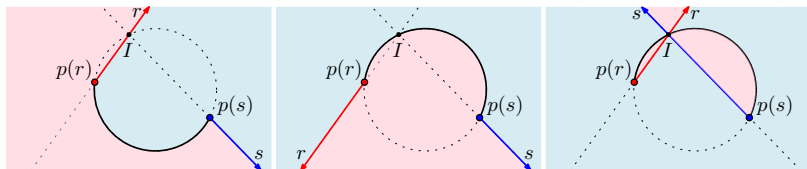
Definition

Given a ray r and a point $x \in \mathbb{R}^2$, the **angular distance** from x to r , $d_{\angle}(x, r)$, is the minimum counterclockwise angle α from r to a ray with apex $p(r)$ passing through x .



Definition

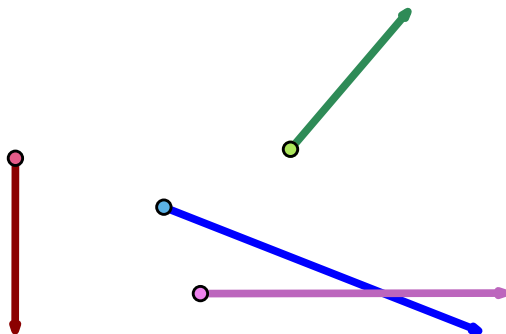
Given two rays r and s , their **angular bisector**, $b_{\angle}(r, s)$, is the curve delimiting the points closer to r and the points closer to s .



Rotating Rays Voronoi Diagram (RVD)

Definition

Given a set of rays \mathcal{S} .

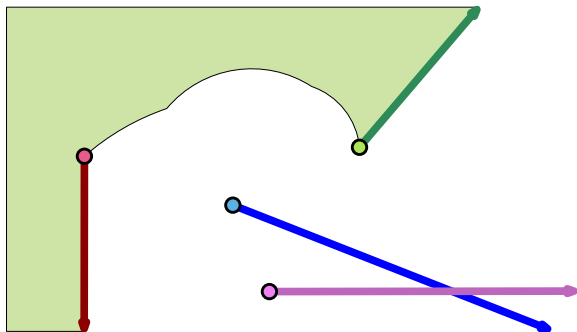


Rotating Rays Voronoi Diagram (RVD)

Definition

Given a set of rays \mathcal{S} . The **Voronoi region** of a ray $r \in \mathcal{S}$ is:

$$\text{vreg}(r) := \{ x \in \mathbb{R}^2 \mid \forall s \in \mathcal{S} \setminus \{r\} : d_{\angle}(x, r) < d_{\angle}(x, s) \}.$$

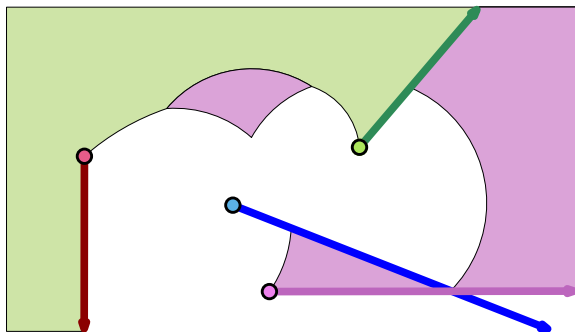


Rotating Rays Voronoi Diagram (RVD)

Definition

Given a set of rays \mathcal{S} . The **Voronoi region** of a ray $r \in \mathcal{S}$ is:

$$\text{vreg}(r) := \{x \in \mathbb{R}^2 \mid \forall s \in \mathcal{S} \setminus \{r\} : d_{\angle}(x, r) < d_{\angle}(x, s)\}.$$



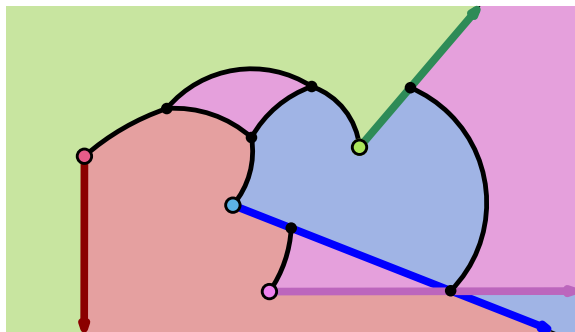
Rotating Rays Voronoi Diagram (RVD)

Definition

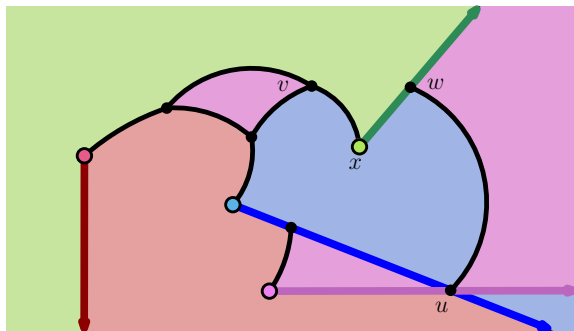
Given a set of rays \mathcal{S} . The **Voronoi region** of a ray $r \in \mathcal{S}$ is:

$$\text{vreg}(r) := \{x \in \mathbb{R}^2 \mid \forall s \in \mathcal{S} \setminus \{r\} : d_{\angle}(x, r) < d_{\angle}(x, s)\}.$$

The **Rotating Rays Voronoi Diagram** of \mathcal{S} is the subdivision of \mathbb{R}^2 in Voronoi regions. **RVD(\mathcal{S})** is the graph structure of the diagram.

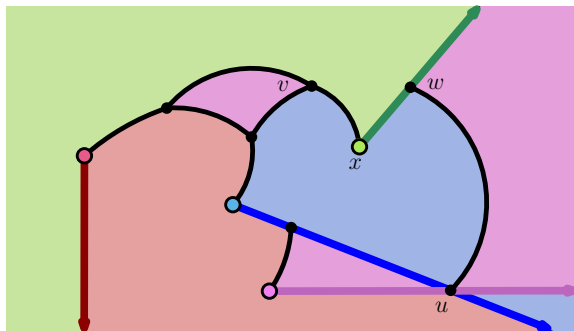


Properties



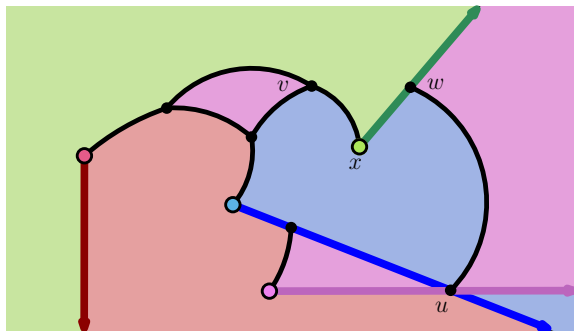
- $\text{RVD}(\mathcal{S})$ has different types of vertices and edges.

Properties



- ▶ $\text{RVD}(\mathcal{S})$ has different types of vertices and edges.
- ▶ A region can have many faces; exactly one is unbounded.

Properties



- ▶ $\text{RVD}(\mathcal{S})$ has different types of vertices and edges.
- ▶ A region can have many faces; exactly one is unbounded.
- ▶ $\text{RVD}(\mathcal{S})$ is connected.

Table of Contents

Introduction

RVD Definitions & Properties

RVD in the Plane

RVD of a Convex Polygon

Diagram Complexity: Lower bound

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $\Omega(n^2)$ worst case complexity.

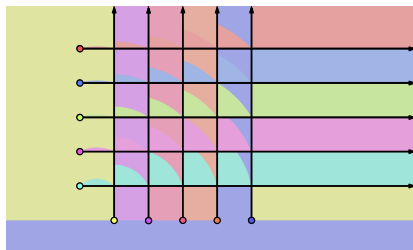


Diagram Complexity: Lower bound

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $\Omega(n^2)$ worst case complexity.

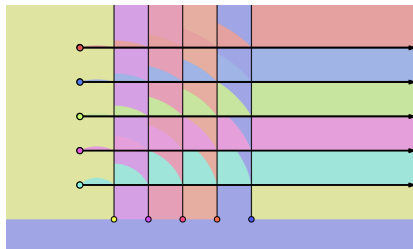


Diagram Complexity: Lower bound

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $\Omega(n^2)$ worst case complexity.
This is true even if the rays are pairwise non-intersecting.

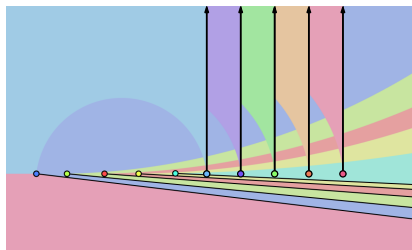
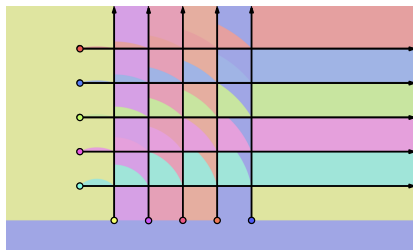


Diagram Complexity: Lower bound

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $\Omega(n^2)$ worst case complexity.
This is true even if the rays are pairwise non-intersecting.

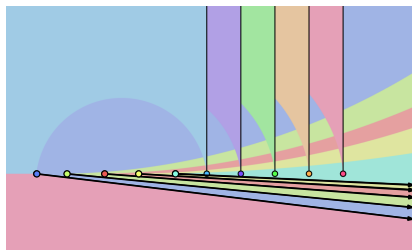
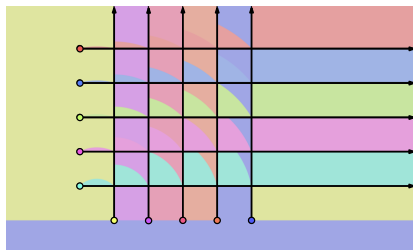


Diagram Complexity: Lower bound

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $\Omega(n^2)$ worst case complexity.
This is true even if the rays are pairwise non-intersecting.

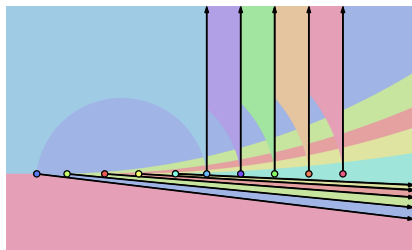
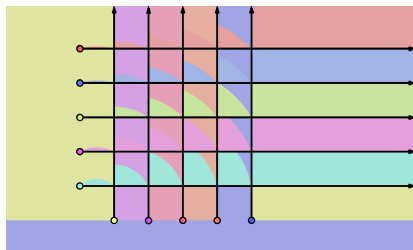
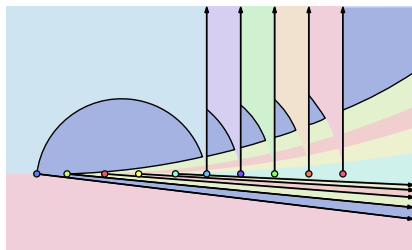
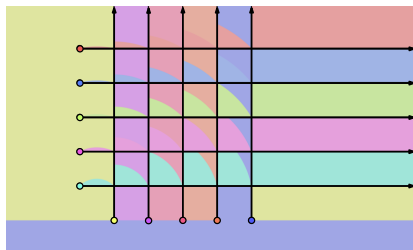


Diagram Complexity: Lower bound

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $\Omega(n^2)$ worst case complexity.
This is true even if the rays are pairwise non-intersecting.



Region Complexity

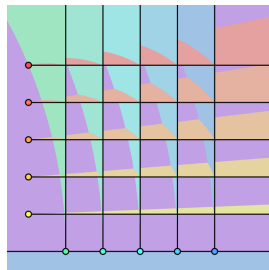
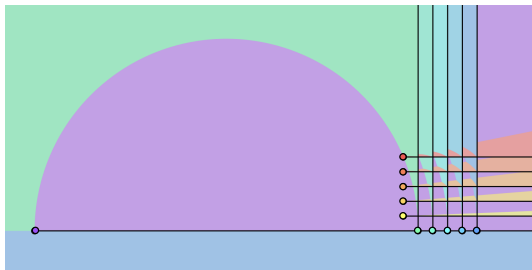
Theorem

A region of $\text{RVD}(S)$ has $\Theta(n^2)$ worst case complexity.

Region Complexity

Theorem

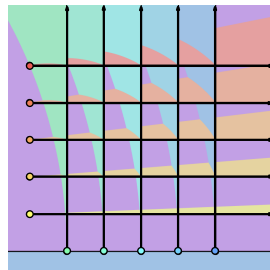
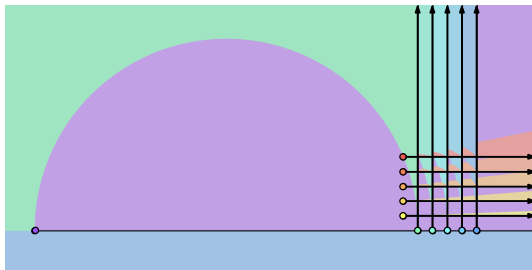
A region of $\text{RVD}(S)$ has $\Theta(n^2)$ worst case complexity.



Region Complexity

Theorem

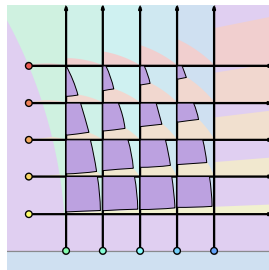
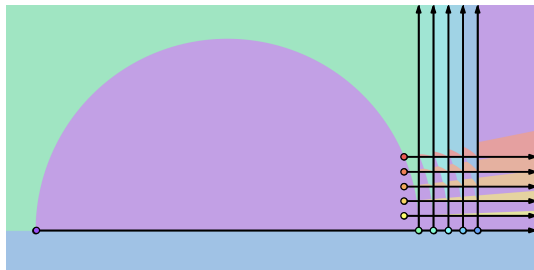
A region of $\text{RVD}(S)$ has $\Theta(n^2)$ worst case complexity.



Region Complexity

Theorem

A region of $\text{RVD}(S)$ has $\Theta(n^2)$ worst case complexity.



Complexity upper bound & Algorithm

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $O(n^{2+\epsilon})$ complexity $\forall \epsilon > 0$.

- ▶ Lower envelopes of distance functions in 3-space [Sharir 1994].

Complexity upper bound & Algorithm

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $O(n^{2+\epsilon})$ complexity $\forall \epsilon > 0$.
Further, $\text{RVD}(\mathcal{S})$ can be constructed in $O(n^{2+\epsilon})$ time.

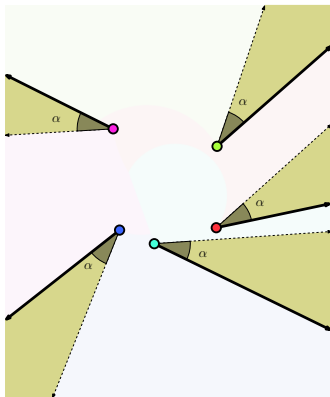
- ▶ Lower envelopes of distance functions in 3-space [Sharir 1994].

Complexity upper bound & Algorithm

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $O(n^{2+\epsilon})$ complexity $\forall \epsilon > 0$.
Further, $\text{RVD}(\mathcal{S})$ can be constructed in $O(n^{2+\epsilon})$ time.

- Lower envelopes of distance functions in 3-space [Sharir 1994].



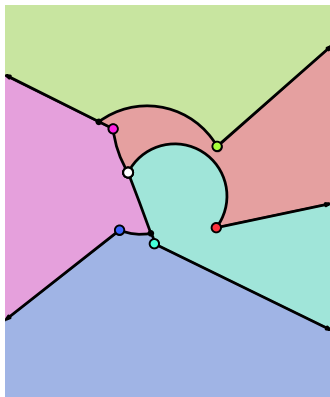
Minimum angle α^* to illuminate \mathbb{R}^2

Complexity upper bound & Algorithm

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $O(n^{2+\epsilon})$ complexity $\forall \epsilon > 0$.
Further, $\text{RVD}(\mathcal{S})$ can be constructed in $O(n^{2+\epsilon})$ time.

- Lower envelopes of distance functions in 3-space [Sharir 1994].



Minimum angle α^* to illuminate \mathbb{R}^2

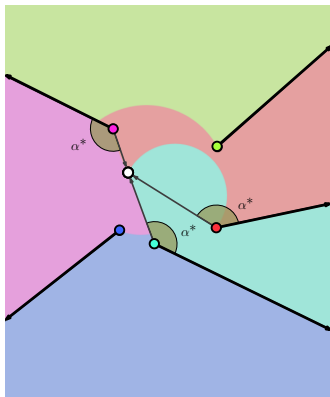
1. Construct $\text{RVD}(\mathcal{S})$. $O(n^{2+\epsilon})$ time.
2. Traverse $\text{RVD}(\mathcal{S})$. Linear time.

Complexity upper bound & Algorithm

Theorem

Given a set \mathcal{S} of n rays $\text{RVD}(\mathcal{S})$ has $O(n^{2+\epsilon})$ complexity $\forall \epsilon > 0$.
Further, $\text{RVD}(\mathcal{S})$ can be constructed in $O(n^{2+\epsilon})$ time.

- Lower envelopes of distance functions in 3-space [Sharir 1994].



Minimum angle α^* to illuminate \mathbb{R}^2

1. Construct $\text{RVD}(\mathcal{S})$. $O(n^{2+\epsilon})$ time.
 2. Traverse $\text{RVD}(\mathcal{S})$. Linear time.
- $\alpha^* \in (2\pi/n, 2\pi)$

Table of Contents

Introduction

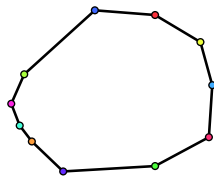
RVD Definitions & Properties

RVD in the Plane

RVD of a Convex Polygon

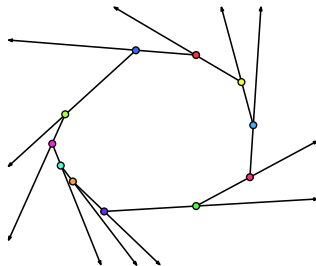
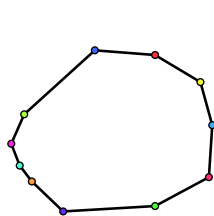
Brocard Illumination of Polygon

- Input: A convex polygon P with n vertices.



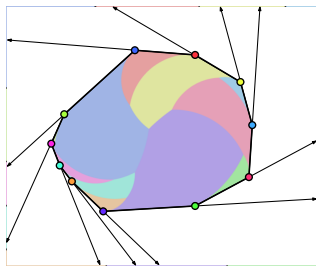
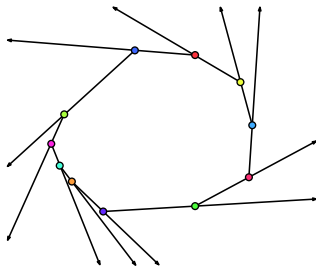
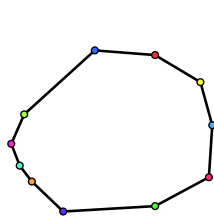
Brocard Illumination of Polygon

- ▶ Input: A convex polygon P with n vertices.
- ▶ Obtain a set of n edge-aligned rays \mathcal{S}_P



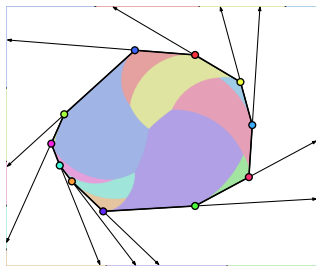
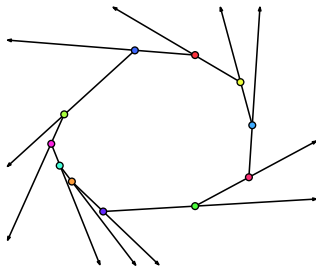
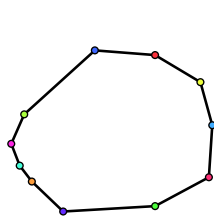
Brocard Illumination of Polygon

- ▶ Input: A convex polygon P with n vertices.
- ▶ Obtain a set of n edge-aligned rays \mathcal{S}_P
- ▶ Output: $\text{PRVD}(\mathcal{S}_P) := \text{RVD}(\mathcal{S}_P) \cap P$.



Brocard Illumination of Polygon

- ▶ Input: A convex polygon P with n vertices.
- ▶ Obtain a set of n edge-aligned rays \mathcal{S}_P
- ▶ Output: $\text{PRVD}(\mathcal{S}_P) := \text{RVD}(\mathcal{S}_P) \cap P$.
- ▶ Output: Brocard angle of P .



Algorithm outline

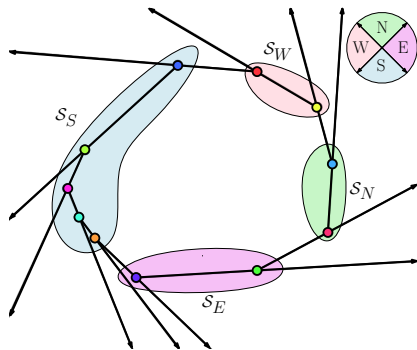
1. **Divide** \mathcal{S}_P into 4 sets of rays.
2. **Construct** the diagrams of the 4 sets.
3. **Merge** the 4 diagrams to obtain $\text{PRVD}(\mathcal{S}_P)$.

Algorithm outline

1. **Divide** \mathcal{S}_P into 4 sets of rays.
2. **Construct** the diagrams of the 4 sets.
3. **Merge** the 4 diagrams to obtain $\text{PRVD}(\mathcal{S}_P)$.

Step 1.

Partition \mathcal{S}_P into 4 sets $\mathcal{S}_N, \mathcal{S}_W, \mathcal{S}_S$ and \mathcal{S}_E depending on the direction of the rays.



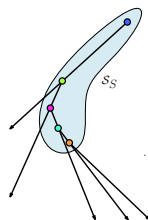
Constructing the 4 diagrams

Step. 2

For each \mathcal{S}_d , $d \in \{N, W, S, E\}$:

Use Hamiltonian **Abstract Voronoi Diagrams**.
[Klein 1989, Klein & Lingas 1994]

- For each $\mathcal{S}' \subseteq \mathcal{S}_d^r$ satisfy a set of axioms.



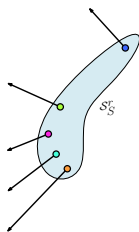
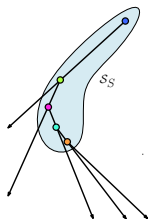
Constructing the 4 diagrams

Step. 2

For each \mathcal{S}_d , $d \in \{N, W, S, E\}$: obtain a set \mathcal{S}_d^r in which every ray of \mathcal{S}_d is rotated by $-\pi/2$.

Use Hamiltonian **Abstract Voronoi Diagrams**.
[Klein 1989, Klein & Lingas 1994]

- For each $\mathcal{S}' \subseteq \mathcal{S}_d^r$ satisfy a set of axioms.



Constructing the 4 diagrams

Step. 2

For each \mathcal{S}_d , $d \in \{N, W, S, E\}$: obtain a set \mathcal{S}_d^r in which every ray of \mathcal{S}_d is rotated by $-\pi/2$.

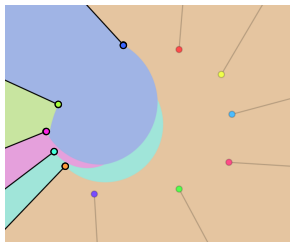
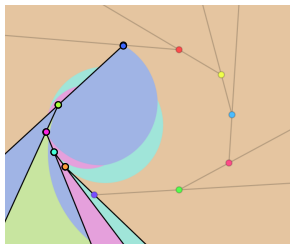
Use Hamiltonian **Abstract Voronoi Diagrams**.
[Klein 1989, Klein & Lingas 1994]

- For each $\mathcal{S}' \subseteq \mathcal{S}_d^r$ satisfy a set of axioms.

Lemma

$\text{RVD}(\mathcal{S}_d^r)$ is a tree of $\Theta(|\mathcal{S}_d^r|)$ complexity.

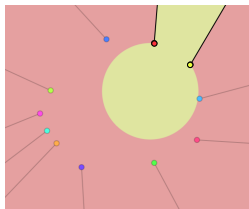
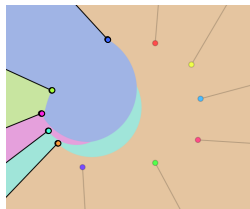
$\text{RVD}(\mathcal{S}_d^r)$ can be constructed in $\Theta(|\mathcal{S}_d^r|)$ time.



Step 3. Merging the 4 diagrams

Step 3.a.

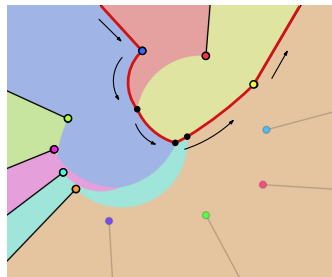
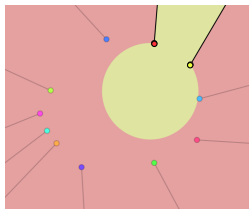
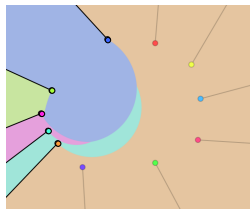
Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$



Step 3. Merging the 4 diagrams

Step 3.a.

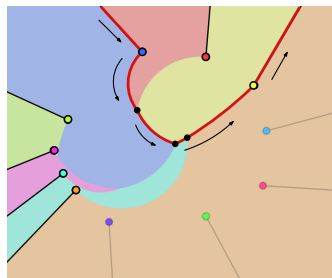
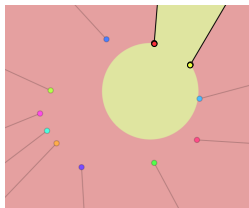
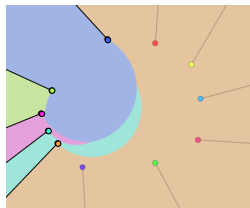
Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.



Step 3. Merging the 4 diagrams

Step 3.a.

Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.
Respectively $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$.



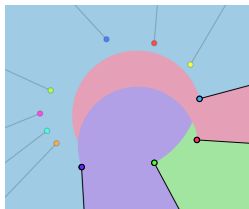
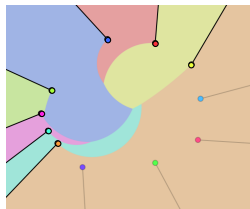
Step 3. Merging the 4 diagrams

Step 3.a.

Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.
Respectively $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$.

Step 3.b.

Merge $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$ with $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$ confined into P .
Obtain $\text{PRVD}(\mathcal{S}_P)$.



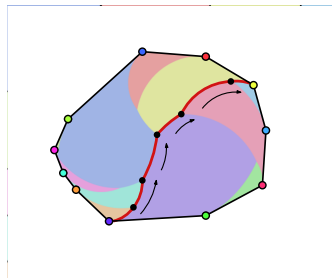
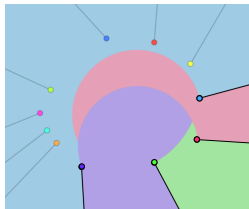
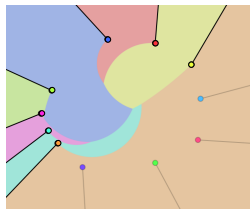
Step 3. Merging the 4 diagrams

Step 3.a.

Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.
Respectively $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$.

Step 3.b.

Merge $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$ with $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$ confined into P .
Obtain $\text{PRVD}(\mathcal{S}_P)$.



Step 3. Merging the 4 diagrams

Step 3.a.

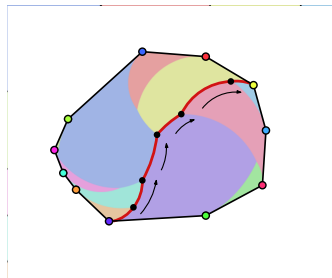
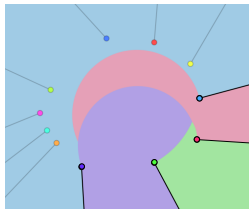
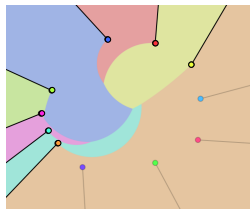
Merge $\text{RVD}(\mathcal{S}_W^r)$ with $\text{RVD}(\mathcal{S}_S^r)$ into $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$.

Respectively $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$. $O(n)$ time

Step 3.b.

Merge $\text{RVD}(\mathcal{S}_W^r \cup \mathcal{S}_S^r)$ with $\text{RVD}(\mathcal{S}_E^r \cup \mathcal{S}_N^r)$ confined into P .

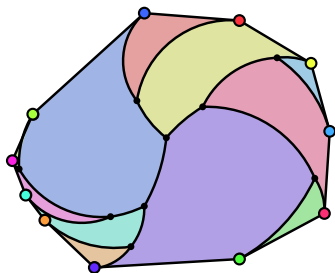
Obtain $\text{PRVD}(\mathcal{S}_P)$. $O(n)$ time



Finding the Brocard angle

Theorem

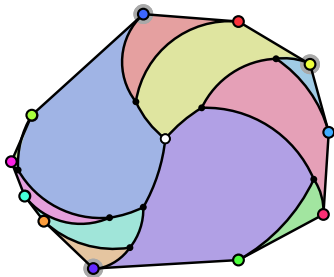
$\text{PRVD}(\mathcal{S}_P)$ can be constructed $\Theta(n)$ time.



Finding the Brocard angle

Theorem

$\text{PRVD}(\mathcal{S}_P)$ can be constructed $\Theta(n)$ time.



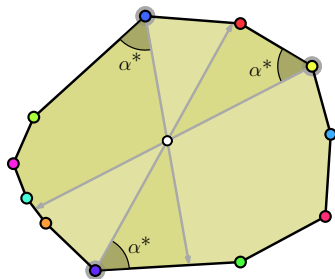
Brocard Illumination of P

1. Construct $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.
2. Traverse $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.

Finding the Brocard angle

Theorem

$\text{PRVD}(\mathcal{S}_P)$ can be constructed $\Theta(n)$ time.



Brocard Illumination of P

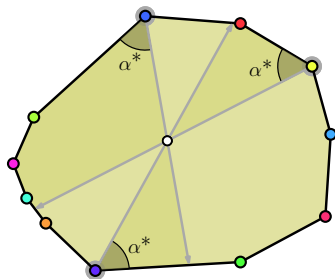
1. Construct $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.
2. Traverse $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.

► Three α^* -floodlights suffice.

Finding the Brocard angle

Theorem

$\text{PRVD}(\mathcal{S}_P)$ can be constructed $\Theta(n)$ time.



Brocard Illumination of P

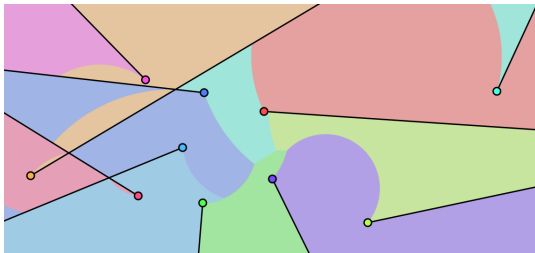
1. Construct $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.
2. Traverse $\text{PRVD}(\mathcal{S}_P)$. $\Theta(n)$ time.

- ▶ Three α^* -floodlights suffice.
- ▶ $\alpha^* \in (0, \pi/2 - \pi/n]$.

Summary and open questions

Summary

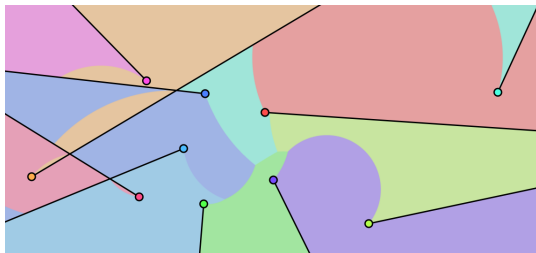
- ▶ RVD: definition, useful in Floodlight Illumination.
- ▶ RVD in \mathbb{R}^2 : properties, complexity & algorithm.
- ▶ Brocard Illumination of convex polygons: optimal $\Theta(n)$ time.



Summary and open questions

Summary

- ▶ RVD: definition, useful in Floodlight Illumination.
- ▶ RVD in \mathbb{R}^2 : properties, complexity & algorithm.
- ▶ Brocard Illumination of convex polygons: optimal $\Theta(n)$ time.



Open Questions

- ▶ Gap in the complexity of $\text{RVD}(\mathcal{S})$ in \mathbb{R}^2 : $\Omega(n^2) - O(n^{2+\epsilon})$
- ▶ Extend our approach to other classes of polygons.